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Stereographic Projection in the Joint Surveillance System

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STEREOGRAPHIC PROJECTION IN THE JOINT SURVEILLANCE SYSTEM

SEPTEMBER 1976

Prepared for

DEPUTY FOR SURVEY LANCE AND HAVIGATION STSTEMS

ELECTRONIC SYSTEMS DIVISION

AIR FORCE SYSTEMS COMMAND

UNITED STATES AIR FORCE

Hanscom Air Force Base, Bedford, Massachusetts



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The stereographic projection process consists of using slant range, azimuth and height information to obtain radar coordinates, and transformation of the radar coordinates to obtain coordinates on a common plane.

This report describes analysis that was performed on the stereographic projection process. The results indicate that the SAGE/BUIC equations for stereographic ground range produce unacceptably large registration errors when extended to a

20. ABSTRACT (Concluded)

large region. The results further indicate that the error can be corrected by a simple modification of the SAGE/BUIC equations.

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SECTION I

INTRODUCTION

In air defense and air traffic control systems, data from the system radars are stereographically projected onto a common coordinate plane for presentation to system operators. The stereographic projection of radar data involves two steps; stereographic projection using slant range, azimuth and height information to obtain polar coordinates in a plane of projection centered at the radar site, and transformation of the radar coordinates into cartesian coordinates on a common coordinate plane.

The stereographic projection and transformation process is mathematically complex. Because of the computational complexity, several assumptions and approximations have been made to expedite processing time without unduly sacrificing accuracy. The present SAGE/BUIC equations for computing radar coordinates, although satisfactory for their intended usage, introduce unacceptable registration errors when extended to large regions as will be encountered in the Joint Surveillance System (JSS).

This report describes analysis that was performed on the stereo-graphic projection process. Equations for obtaining stereographic ground range are derived. The derivation indicates that the SAGE/BUIC ground range equation lacks a scale factor vital to proper registration in large regions. The scale factor is a function of the radius of the earth at a radar site and the radius of the conformal sphere.

SECTION II

EFFECT OF THE CONFORMAL SPHERE ON STEREOGRAPHIC PROJECTION

STEREOGRAPHIC PROJECTION

Stereographic projection is a method for mapping points in space onto a plane tangent to a sphere. This sphere is termed the conformal sphere and its radius is arbitrary. Figure I depicts the projection geometry for a cross section of the sphere. The cross section is obtained by passing a plane through the center of the sphere, the aircraft, and the point of tangency. The intersection of this plane and the sphere is a great circle. Mapping of point A in space onto the tangent plane BB' results in the stereographic ground range DT. DT is obtained by passing a line from point 0, opposite the point of tangency D, through point P, the point of projection, and intersecting the tangent plane. Point P is the intersection of the line containing point A and the center of the earth, point C, and the great circle. If angle DCP is designated as ψ , then angle DOP equals $\psi/2$ since DC=CO=CP. The stereographic ground range DT is determined as follows.

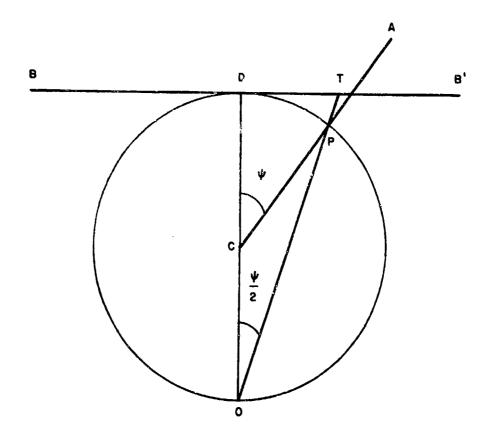
$$DT = DO \tan \left(\frac{\psi}{2}\right) \tag{1}$$

If DT is defined as R and DC, CO, CP are defined as $E_{\rm c}$, then equation (1) takes the form:

$$R = 2E_{c} \tan\left(\frac{\psi}{2}\right)$$

$$= 2E_{c} \left[\frac{1 - \cos\psi}{1 + \cos\psi}\right]^{1/2} \tag{2}$$

The stereographic ground range R is therefore directly proportional to the radius of the conformal sphere $\mathbf{E}_{\mathbf{c}}$.



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Figure I. STEREOGRAPHIC PROJECTION

THE RADAR PLANE

Radar data are stereographically projected onto a plane centered at the reporting radar site and tangent to the conformal sphere. The plane will be termed the radar plane. The coordinate axes of the radar plane are oriented such that the positive Y axis is directed toward true north and the positive X axis towards east. Figure II shows the orientation of the coordinate axes on the radar plane. An aircraft's location on the plane is expressed in polar coordinates. The range R is the stereographic ground range, and the azimuth angle 0 is the azimuth of the radar return. Azimuth angles are measured clockwise from the positive Y axis.

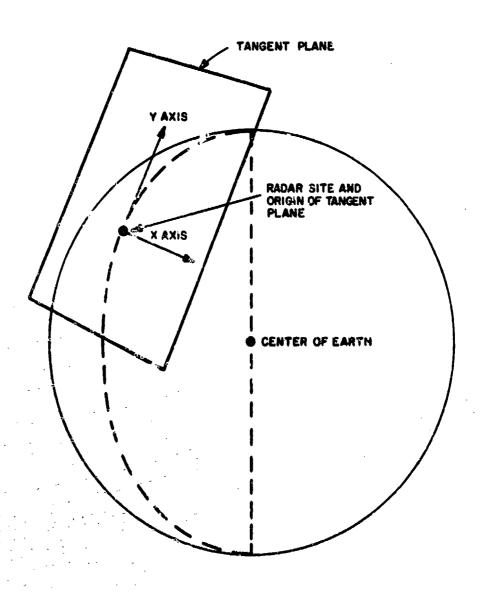
DETERMINATION OF STEREOGRAPHIC GROUND RANGE

Radar slant range, height of the aircraft above sea level and elevation of the site above sea level are used to determine the stereographic ground range of an aircraft on the radar plane. The angle ψ between the radar site, the center of the earth and the aircraft are used in equation (2) to calculate the stereographic ground range. The angle ψ can be calculated if the earth is assumed to be spherical. Figure III illustrates the radar geometry for a cross section of a spherical earth where E_g is the radius of the earth, h is the site elevation, S is the measured slant range and H is the aircraft height. From Figure III the angle ψ may be calculated from the law of cosines.

$$S^{2} = (E_{s} + h)^{2} + (E_{s} + H)^{2} - 2(E_{s} + h)(E_{s} + H) \cos \psi$$

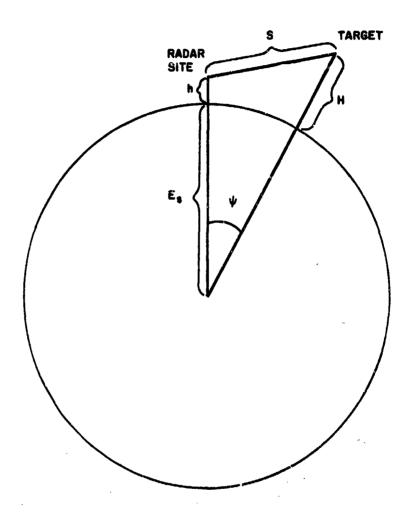
$$\cos \psi = 1 + \frac{(H - h)^{2} - S^{2}}{2(E_{s} + h)(E_{s} + H)}$$

$$= 1 - \frac{F^{2}}{2(E_{s} + h)(E_{s} + H)}$$
(3)



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Figure II COORDINATE AXES ON RADAR PLANE



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Figure III RADAR OBSERVATION GEOMETRY

where:

$$F^2 = S^2 - (H - h)^2$$

Substituting the results of equation (3) into equation (2), the ground range R may be obtained as follows.

$$R = 2E_{c} \left[\frac{F^{2}}{4(E_{s} + h)(E_{s} + H) - F^{2}} \right]^{1/2}$$

$$= \frac{E_{c}F}{E_{s}} \left[1 + \frac{H + h}{E_{s}} + \frac{Hh}{E_{s}^{2}} - \frac{F^{2}}{4E_{s}^{2}} \right]^{-1/2}$$
(4)

Reference 1 page 7 presents the SAGE/BUIC formulation of the ground range wherein it is assumed that \mathbf{E}_{c} and \mathbf{E}_{s} are equal and thus cancel. It will be shown that for the large regions that will be encountered in the JSS system, this assumption results in unacceptable registration errors.

APPROXIMATIONS TO GROUND RANGE

The accuracy of typical common digitizer search radar outputs is 0.25 nmi in range and 0.18° in azimuth. Registration errors are a combination of data errors, radar site location errors, and errors due to approximations in the stereographic projection process. Since equation (4) is computationally complex, an approximation which does not unduly sacrifice accuracy is used to expedite processing time. A maximum error, induced by approximation, of 0.18 nmi provides a reasonable compromise between processing requirements and registration accuracy. Four approximations are presented in this section; the series approximation, the first order approximation, the JSS approximation and the current SAGE/BUIC approximation.

The Series Approximation

Equation (4) may be written in the following form.

$$R = \frac{\frac{E_{c}F}{E_{s}}}{E_{s}\left(1 + \frac{H + h}{E_{s}} + \frac{Hh}{E_{s}^{2}} - \frac{F^{2}}{4E_{s}^{2}}\right)^{1/2}}$$
 (5)

The term within brackets in the denominator of equation (5) may then be expressed by the following series expansion.

$$(1 + x)^n = 1 + nx + \frac{n(n-1)x^2}{2!} + \dots$$

where:

$$x = \left(\frac{H + h}{E_s} + \frac{Hh}{E_s^2} - \frac{F^2}{4E_s^2}\right) \quad \text{and} \quad n = \frac{1}{2}$$

The maximum value of x encountered in a JSS region is 0.005. Since x < 1, all but the first order term of the series may be ignored and equation (5) may be expressed as follows.

$$R \approx \frac{E_{c}F}{E_{s}\left(1 + \frac{H + h}{2E_{s}} + \frac{Hh}{2E_{s}^{2}} - \frac{F^{2}}{8E_{s}^{2}}\right)}$$
 (6)

The First Order Approximation

The bracketed term in the demoninator of equation (6) contains a first order term and two second order terms. The maximum value of $\frac{H+h}{2E_g}$ is 0.00248, the maximum value of $\frac{hH}{2E_g^2}$ is 0.000000721, and the

maximum value of $\frac{F^2}{8E_g^2}$ is 0.000424. Since the second order terms are

smaller than the first order term, they may be neglected and equation (6) may be expressed as follows.

$$R = \frac{E_c F}{E_s \left(1 + \frac{H + h}{2E_s}\right)}$$
 (7)

The JSS Approximation

By replacing the aircraft height term (H) in the demoninator of equation (7) by a constant, equation (7) may be expressed as follows.

$$R \approx \frac{F_c F}{F_s \left(1 + \frac{(H_{m/2})^{+ h}}{2E_s}\right)}$$
 (8)

where:

 $H_{\rm m}$ is the maximum expected aircraft altitude equal to 100,000 ft. Equation (8) may be expressed in the following form.

where:

$$C = \frac{E_{c}}{E_{s}\left(1 + \frac{(ii_{m/2}) + h}{2E_{s}}\right)}$$

This is a particularly good approximation since the stereographic ground range is obtained from a simple scale multiplication of the quantity F. This greatly decreases the time required to process radar returns. The constant C is adaptation defined on a site-by-site basis.

The Current SAGE/BUIC Approximation

If $\boldsymbol{E}_{_{\mathbf{C}}}$ is assumed to be the same as $\boldsymbol{E}_{_{\mathbf{R}}}$ equation (8) is expressed as follows.

$$R = \frac{F}{\left(1 + \frac{\left(\frac{H_{m/2}}{2F_{g}}\right) + h}{2F_{g}}\right)}$$
 (9)

EARTH MODEL

The earth is not a perfect sphere. Therefore, for precise calculations of stereographic ground range, a model for the geometric shape of the earth must be adopted. An appropriate first order representation is an ellipsoid. The ellipsoid is generated by revolving an ellipse about its semiminor axis. The earth model can therefore be specified by its semimajor axis or equatorial radius $\mathbf{E}_{\mathbf{q}}$ and the eccentricity e. A cross section of the adopted earth model is shown in Figure IV. The eccentricity is defined as follows.

$$e^2 - 2f - f^2$$
 (10)

vhere:

$$e = \frac{E_q - E_p}{E_q}$$

E is the semiminor axis or polar radius

The International Ellipsoid of 1924 will be used for the purpose of this report; thus, E_q equals 3444.054 nmi and e^2 equals .00672267.

Mapping from Ellipsoid to Sphere

The stereographic projection equations have been derived for a sphere. It is therefore necessary to transform points on or above the ellipsoid to points on or above the sphere. This transformation must be conformal, i.e., angle preserving, if the final stereographic projection is to be conformal. Reference 2 page 86 derives the relationship between the ellipsoid and the conformal sphere. The mapping of points on or above a location on the ellipsoid onto the conformal sphere is performed as follows.

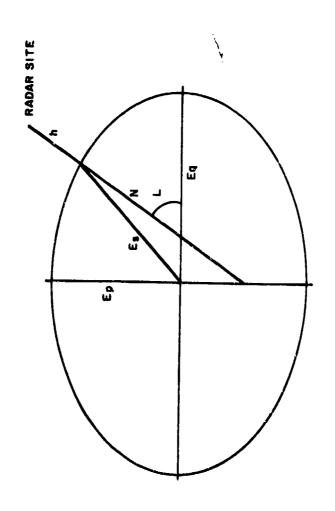


Figure IV A CROSS SECTION OF THE ADOPTED EARTH MODEL

$$\tan\left(\frac{\pi}{4} + \frac{\Phi}{2}\right) = \tan\left(\frac{\pi}{4} + \frac{L}{2}\right) \cdot \left[\frac{1 - \operatorname{esinL}}{1 + \operatorname{esinL}}\right]^{e/2} \tag{11}$$

In these equations:

- L, λ are the geographical latitude and longitude of the point on the ellipsoid
- Φ , λ are the latitude and longitude of the corresponding point on the conformal sphere. The latitude Φ is called the conformal latitude.
- e is the eccentricity of the earth.

Since the mapping process involves only a transformation of latitudes, the stereographic projection equations are valid for the ellipsoid if the conformal latitude (Φ) is used in place of the geographic latitude (L).

Radius of the Earth to a Radar Site

In determination of the stereographic ground range, a spherical earth was used to compute the angle that subtends the radar site and the target. Since the earth is actually modeled by an ellipsoid, the use of a spherical earth in calculating stereographic ground range without introducing corrections to slant range and height, to allow for the conformal projection, will introduce a certain amount of error. To minimize this error, the radius of the spherical earth E is set equal to the distance from the center of the ellipsoid to the surface of the ellipsoid at the radar site as shown in Figure IV. The distance E is calculated as follows.

$$E_{s} = (x_{2}^{2} + Y_{s}^{2})^{1/2}$$
 (12)

where:

$$Y_q = N \cos L$$

 $Y_q = (1 - e^2) N \sin L$

$$N = \frac{E_{q}}{(1 - e^{2} \sin^{2} L)^{1/2}}$$

L is the geographic latitude.

Table I gives the radius of the Earth at latitudes between 0 and 90 degrees.

Table I

Earth Radius Versus Latitude

Geographic Latitude	Earth Radius (nmi)
0°	3444.054
10°	3443.707
20*	3442.708
30°	3441.173
40°	3439,286
50°	3437.273
60*	3435.375
70°	3433.824
80*	3432.810
90•	3432.458

Calculations show that the resulting error is greatest for a target north or south of the radar and does not exceed \pm 0.03 nmi at a range of 250 nmi.

THE COMMON COORDINATE PLANE

In a large air surveillance region such as will be encountered in the JSS, several radars are linked together in order to display a composite air surveillance picture. It is therefore necessary to transform coordinates on the individual radar planes to coordinates on a common plane. The transformation process requires that the coordinates of the radars on the common plane and that angular rotations between the radar planes and the common plane be known.

The origin of the common plane or region center is defined as the center of the smallest circle that will circumscribe all radars tied into the air surveillance region. The common plane is tangent to the conformal sphere. The coordinates axes are oriented such that the positive Y axis is directed towards true north and the positive X axis is directed towards east. Coordinates on the common plane are expressed in cartesian coordinates.

Radar Coordinates on the Common Plane

A radar site or other known location can be stereographically projected onto the common coordinate plane. Reference 3 page 53 derives the equations necessary to project a point on the conformal sphere onto the common coordinate plane. The rectangular coordinates of a radar site or other known location $\mathbf{X}_{\mathbf{r}}$, $\mathbf{Y}_{\mathbf{r}}$ on the common plane are obtained as follows.

$$x_r = 2E_c \frac{s \ln \Delta \cos \phi}{1 + s \ln \phi \sin \phi} + \cos \phi \cos \phi \cos \Delta \lambda$$
 (13)

$$Y_{r} = \frac{2E_{c}}{1 + \sinh \sin \phi_{0} + \cos \phi \cos \phi_{0} \cos \delta \lambda}$$
 (14)

where:

φ, λ are the conformal latitude and longitude of the point to be projected

 ϕ_0 , λ_0 are the conformal latitude and longitude of the region center

 $\Delta \lambda = \lambda_0 - \lambda$ if longitudes are measured positive west of the prime meridian

= $\lambda - \lambda_0$ if longitudes are measured positive east of the prime meridian

Angular Rotation

As indicated in reference 3 page 6, an angular rotation of the radar plane with respect to the common coordinate plane is necessary for the transformation process. The effect of the rotation is to make the axes of the radar plane more nearly parallel to the axes of the common plane. The angle of rotation is shown in reference 3 to be:

$$\beta = \tan^{-1} \left[\frac{-(\sin\phi + \sin\phi_0)\sin\Delta\lambda}{\cos\phi\cos\phi_0 + (1 + \sin\phi\sin\phi_0)\cos\Delta\lambda} \right]$$
 (15)

Transformation of Radar Coordinates on the Common Plane

The equations for transformation of radar coordinates to coordinates in the common coordinate plane are derived in reference 3 pages 3 - 15. The exact transformation equations involve an infinite series. To lessen the processing requirement without unduly sacrificing accuracy a second order approximation is used. Rectangular coordinates X, Y are obtained as follows.

$$X = X_{g} + K(Rsin(\theta + \beta) + AR^{2}sin[2(\theta + \beta) - \gamma])$$
 (16)

$$Y = Y_{r} + K(R\cos(\theta + \theta) + AR^{2}\cos[2(\theta + \theta) - Y])$$
 (17)

where:

$$K = 1 + \frac{u_r^2}{4E_c^2}$$

$$A = \frac{v_r}{4E_c^2}$$

$$v_r = (x_r^2 + y_r^2)^{1/2}$$

$$y = \tan^{-1}\left(\frac{x_r}{y_r}\right)$$

- R is the stereographic ground range
- θ is the azimuth angle measured clockwise from north at the radar site
- X_r, Y_r are the coordinates of the reporting radar on the common plane

Since the coordinates of an aircraft on the common plane are a function of the stereographic ground range R, any error in the stereographic ground range will appear as a misregistration on the common coordinate plane.

THE CONFORMAL SPHERE

The common coordinate plane and all radar planes are tangent to the conformal sphere. The radius of the conformal sphere is arbitrary, but is chosen to minimize the scale errors that will be encountered in the air surveillance region. Scale errors result in an ang from the ellipsoid to the conformal sphere and in mapping from the conformal sphere onto the tangent plane.

Scale Factor - Ellipsoid to Conformal Sphere

The scale factor associated with mapping from the ellipsoid to the conformal sphere is the ratio of a linear element on the conformal sphere to a corresponding linear element on the ellipsoid. From reference 2 page 86, the scale factor associated with a point of projection is:

$$k_1 = \frac{E_c \cos \phi}{N \cos L} \tag{18}$$

where:

 The scale factor is a function of the radius of the conformal sphere and the conformal and geographic latitude of the point to be projected. The scale factor can be expressed as follows.

$$k_{1} = \frac{E_{c}}{E_{q}} \frac{(1 - e^{2} \sin^{2} L)^{1/2} \cos\phi}{\cos L}$$

$$= \frac{E_{c}}{E_{q}} k_{1}^{r}$$
(19)

Table II gives values of k_1^{ι} for several different latitudes.

Table II

Scale Factor — Ellipsoid to Sphere versus Latitude

Geographic Latitude	Scale Factor k
0°	1.00000000
10°	1.00010071
20°	1.00039099
30°	1.00083667
40°	1.00138493
50°	1.00197024
60°	1.00252293
70°	1.00297314
80°	1.00326821
90°	1.00337838

Scale Factor - Conformal Sphere to Plane

The scale factor associated with mapping from the conformal sphere to the plane of projection is the ratio of a linear element on the plane of projection to a corresponding linear element on the conformal sphere. The scale factor is therefore a function of the angular separation between the origin of the plane and the point of projection. The distance on the sphere between the origin of the plane and the point of projection is calculated as follows.

$$D = E_c \psi \tag{20}$$

The stereographic ground range R is given by equation (1) as follows.

$$R = 2E_{c} \tan\left(\frac{\psi}{2}\right) \tag{21}$$

The scale factor associated with mapping from the conformal sphere to the plane of projection is calculated as follows.

$$k_{2} = \frac{dR/d\psi}{dD/d\psi}$$

$$= \sec^{2}(\frac{\psi}{2})$$

$$= \frac{2}{1 + \cos\psi}$$
(22)

Table III presents the scale factor k_2 as a function of angular separation.

Table III
Scale Factor - Conformal Sphere to Plane versus Angular Separation

Angular Separation	Scale Factor k
0 °	1.00000000
2°	1.00030468
4°	1.00121946
6°	1.00274658
8°	1.00488976
10°	1.00765427
12°	1.01104690
14°	1.01507605
16°	1.01975173
18°	1.02508563
20°	1.03109120

Aircraft and radar locations in the air surveillance region are presented on the common plane. The scale factor $\mathbf{k_2}$, associated with the common plane is a function of the angular separation between the region center and the point of interest. From reference 3 page 23, the angular separation between the region center and a point of

interest can be expressed in terms of their locations on the conformal sphere as follows.

$$\cos \psi = \sin \phi \sin \phi_0 + \cos \phi \cos \phi_0 \cos \Delta \lambda \tag{23}$$

Combining equations (22) and (23) the scale factor k_2 is expressed as follows.

$$k_2 = \frac{2}{1 + \sin\phi \sin\phi_0 + \cos\phi \cos\phi_0 \cos\Delta\lambda}$$
 (24)

Calculation of the Radius of the Conformal Sphere

The total scale factor in mapping a point from the ellipsoid to the common coordinate plane is the product of k_1 and k_2 . The total scale factor is expressed as follows.

$$k = \frac{2E_{c}\cos\phi}{N\cos L(1 + \sin\phi\sin\phi_{0} + \cos\phi\cos\phi_{0}\cos\Delta\lambda)}$$
 (25)

The scale factor expresses the ratio of a linear element on the common coordinate plane to the corresponding element on the ellipsoid. The scale factor therefore represents the ratio of the velocity on the common plane to the corresponding velocity on the ellipsoid. A unity scale factor is highly desirable since velocity on the common plane will represent actual ground speed. The scale error is defined as the difference between the scale factor at a point in the region and a unity scale factor. The scale error ε is expressed as follows.

$$\varepsilon = \frac{2E_{c}\cos\phi}{N\cos L(1 + \sin\phi\sin\phi_{0} + \cos\phi\cos\phi_{0}\cos\Delta\lambda)} - 1$$

$$= E_{c} A - 1$$
(26)

The extent of an air surveillance region is defined by the location of the radars that are tied into it. Since the scale error varies as a function of the location and separation of a point from the region center, it is highly desirable to minimize the maximum scale

errors that will be encountered. From equation (26) the value of the scale error at a point can be varied by varying the radius of the conformal sphere $\mathbf{E}_{\mathbf{C}}$. It is therefore possible to obtain both positive and negative scale errors. To minimize the magnitude of the largest scale error, $\mathbf{E}_{\mathbf{C}}$ is chosen such that the magnitude of the maximum negative scale error is equal to the maximum positive scale error. The radius of the conformal sphere is obtained as follows.

$$\varepsilon_{\min} + \varepsilon_{\max} = 0$$

$$E_{c}A_{\min} - 1 + E_{c}A_{\max} - 1 = 0$$

$$E_{c}(A_{\min} + A_{\max}) - 2 = 0$$

$$E_{c} = \frac{2}{A_{\min} + A_{\max}}$$
(27)

where A_{\min} and A_{\max} are the smallest and largest A calculated for the region center and all radars tied to the region. Substituting equations (19) and (24) into equation (24) the value of A may be calculated as follows.

$$A = \frac{k_1^{\dagger}k_2}{E_q} \tag{28}$$

The values of A_{max} and A_{min} for a given region can therefore be determined from Tables II and III. The following general conclusions can be drawn from examination of the tables.

- 1. A_{\min} usually corresponds to the region center since its value of k_2 is unity.
- 2. A usually corresponds to the most distant radar since it has the largest angular separation. If two radars have the same angular separation, A_{max} will correspond to the more northerly since it will have the larger k_1 value.

Table IV shows values of $E_{\rm c}$ calculated for a region center at a geographic latitude of 45° and radar sites directly north and south of the region center. Table IV shows that the radius of the conformal sphere decreases markedly as the region size increases.

Table IV

E Versus Region Size

Geographic Latitude of Most Distant Radar	Distance From Region Center	E _c _
47°	120.012	3437.561
49°	240 10	3435.787
51°	359.997	3435.963
53°	479.970	3429.088
57°	719.881	3418.170
61°	959.744	3403.004
65°	1199.563	3383.553
43°	120,026	3437.964
41°	240.064	3436.596
39°	360.116	3434.179
37°	480.179	3430.714
33°	720.342	3420.628
29°	960.553	3406.314
25°	1200.808	3387.749

Effect of Ec/Es

The JSS stereographic ground range equation, equation (8), and the current SAGE/BUIC stereographic ground range equation, equation (9), differ by the scale factor $E_{\rm c}/E_{\rm g}$. The effect of $E_{\rm c}/E_{\rm g}$ can be expressed as the difference between the two equations as follows.

$$\delta = F / \left(1 + \frac{H_{m/2} + h}{2F_s} \right) \left(1 - \frac{E_c}{F_s} \right)$$

$$= R \left(1 - \frac{E_c}{E_s} \right)$$
(29)

Since stereographic ground range is transformed into coordinates on the common plane, a difference in the ground ranges will result in a corresponding misregistration on the common plane. The quantity R in equation (29) represents an approximation. Since the design registration error budget in JSS is .18 nmi, R must differ from its actual value by no more than .18 nmi. (A detailed review of the errors induced by an error in R is tayond the scope of this report.) Therefore a difference calculated by equation (29) greater than .36 nmi will guarantee an unacceptable registration error if the SAGE/BUIC stereographic ground range is used. To show the effect of $^{\rm E}{}_{\rm C}/^{\rm E}{}_{\rm S}$ as a function of region size, values of δ are shown in Table V for the radar locations, region center and values of $^{\rm E}{}_{\rm C}$ indicated in Table IV. The value of R was arbitrarily chosen to be 100 and 200 nmi. Region size is defined as the distance of the most distant radar from the region center.

Table V

Difference Between Ground Range Equations 8 and 9 versus Region Size

Geographic Latitude of Most Distant Radar	Approximate Region Size	E _c /E _s	δ(nmi) R=100nmi	δ (nmi) R=200nmi
47°	120	.9999	.009	.018
49°	240	.9995	.049	.098
51°	360	.9988	.120	.239
53°	480	.9978	.221	.442
57°	720	.9948	.517	1.033
61°	960	.9906	.937	1.875
65°	1200	.9852	1,485	2.969
43°	120	.9998	.021	.042
41°	240	.9993	.072	.145
39°	360	.9985	.154	.308
37°	480	.9973	.266	.533
33°	720	.9942	.581	1,163
29°	960	.9898	1.018	2.036
25°	1200	.9842	1.576	3.152

Examination of Table V reveals that for R equal to 200 nmi, values of 8 will exceed .36 nmi for regions somewhere between 360 nmi and 480 nmi. This indicates that the SAGE/BUIC stereographic ground range equation will produce unacceptable results in large regions. Some of the current SAGE/BUIC regions exceed these limits, and all JSS regions will exceed these limits by a considerable margin. Section III of this report is devoted to depicting the registration errors produced by the SAGE/BUIC and JSS stereographic ground range equations in the seven JSS regions.

SECTION III

EFFECT OF THE SAGE/BUIC AND JSS STEREOGRAPHIC GROUND RANGE EQUATIONS ON REGISTRATION

INTRODUCTION

Accurate stereographic projection of radar data onto the common coordinate plane is vital to the operation of air defense and air traffic control systems. Large registration errors seriously downgrade the performance and stability of the active tracking algorithm. For each of the seven JSS regions, simulated radar data was used to demonstrate the effect of the SAGE/BUIC and JSS stereographic ground range equations on registration.

SIMULATED RADAR DATA

Radar slant range and azimuth data were generated for four air-craft locations at altitudes of 30,000, 45,000 and 60,000 ft in each JSS region. Appendix I indicates the algorithm used to produce the data. For a particular radar, a slant range-azimuth pair was generated only if the aircraft was within 250 nmi of the radar and above the radar horizon. Aircraft locations were chosen so that slant ranges for the reporting radars would be greater than 170 nmi.

Radar slant ranges were converted into stereographic ground ranges using the SAGE/BUIC and JSS stereographic ground range equations (equations (8) and (9)). Stereographic ground ranges were transformed into coordinates on the common plane using equations (16) and (17). Since the location of the aircraft was known, actual coordinates on the common plane were computed using equations (13) and (14). The registration error was obtained by taking the magnitude of the difference between the actual coordinates on the common plane and those obtained by the SAGE/BUIC and JSS stereographic ground range equations.

Appendix II presents the data for the seven JSS regions. For each region, there is a Site Data, a Simulated Radar Data, and a Registration Error table. In addition there is a figure showing the location of the region center, radar sites, and aircraft. The following information is given in the tables.

Site Data Table:

- 1. Approximate geographic latitude and longitude of the region center and radar sites.
- 2. Radius of the earth to each radar site.
- 3. Coordinates on the common plane for each radar site.
- 4. The radius of the conformal sphere.

Simulated Radar Data Table:

- 1. The geographic latitude and longitude and altitude of the aircraft in the region.
- 2. The designation of all reporting radars.
- 3. Slant range and azimuth data for all reporting radars.

Registration Error Table:

- Stereographic ground range calculated using the SAGE/BUIC and JSS ground range equations.
- Coordinates on the common plane obtained from the SAGE/ BUIC and JSS ground range equations.
- 3. Coordinates on the common plane obtained from the actual aircraft locations.
- 4. The registration error induced by the SAGE/BUIC and JSS ground range equations.

Examination of the tables in Appendix II reveals that use of the SAGE/BUIC stereographic ground range equation resulted in registration errors that exceeded the .18 nmi JSS registration error budget in all cases tested. Use of the JSS stereographic ground range equation resulted in acceptable registration errors. Table VI summarizes the

TABLE VI WORST-CASE RECISTRATION ERRORS IN EACH JSS RECION

RECISTRATION ERRORS SAGE/BUIC JSS	84 0.016	03 0.010	81 0.019	27 0.002	33 0.015	84 0.031	39 0.030
	0.584	0.703	0.581	0.627	1.433	0.684	0.439
SLANT RANCE (NY)	179.161	181.280	179.547	179.980	179.475	181.173	182.171
CASE #	12	9	6	12	12	12a	6
APPROXIMATE REGION SIZE (NM)	507	582	535	975	778	603	6£7
RADIUS OF THE CONFORMAL SPHERE	3428.842	3425.636	3430,619	3428.877	172°1176	3423,829	225*1275
JSS REGION	MATHEAST	MORTHWEST	SOUTHEAST	SOUTHWEST	EASTERN	WESTERN CANADA	ALASKAN

worst case results for slant ranges of approximately 180 nmi in each of the seven JSS regions.

The omission of the factor E_c/E_s is responsible for the large registration errors produced by the SAGE/BUIC stereographic ground range equation. For a particular region, the value of E_c is constant. The most southerly radar will have the largest value of E_s . Therefore the value of δ as calculated by equation (29) will be largest for the most southerly radar. This indicates that the worst case errors will be produced by the most southerly radar, and the best case errors by the most sortherly. Further examination of Appendix II supports this conclusion.

SECTION IV

CONCLUSIONS

The scale factor E_c/E_s should be included in the stereographic ground range equation to avoid large registration errors. This is especially important in large regions. The JSS stereographic ground range equation for processing returns with height data is:

$$R = \frac{E_c (S^2 - H^2)^{1/2}}{E_s \left(1 + \frac{H_{m/2} + h}{2E_s}\right)}$$

The present SAGE/BUIC stereographic ground range equations should be modified to reflect the scale factor $\mathbf{E_c/E_s}$. The modification would require a change in the adaptation parameters on a site-by-site basis.

REFERENCES

- 1. J.J. Burke, An Improved Stereographic Coordinate Conversion Approximation for Radar Data Processing, MTR-2548, Contract F19628-73-C-0001, The MITRE Corporation, Bedford, MA, January 1973.
- 2. P. Thomas, Conformal Projections in Geodesy and Cartography, Special Publication 251, U.S. Coast and Geodetic Survey, 1952.
- 3. J.J. Burke, Stereographic Projection of Radar Data in a Netted Radar System, ESD-TR-73-210, AD 771544, November 1973.

APPENDIX I

GENERATION OF SLANT RANGE AND AZIMUTH DATA

Radar slant range and azimuth data are calculated for aircraft locations using vector operations. The vector $\underline{\mathbf{v}}$ from the center of the earth to a point on or above the ellipsoid is calculated as follows.

$$\underline{V} = \begin{cases} X_{v} = (N + H)\cos L\cos \lambda \\ Y_{v} = (N + H)\cosh \sinh \lambda \\ Z_{v} = [N(1 - e^{2}) + H]\sinh \lambda \end{cases}$$
 (A-1)

where:

H is the height of the point above the ellipsoid λ is measured positive east of the prime meridian. The slant range S is computed as follows.

$$\underline{S} = \underline{T} - \underline{R}$$

$$S = |\underline{S}| \qquad (A-2)$$

where:

T, R are vectors from the center of the earth to the aircraft and radar respectively.

The aircraft must be above the radar horizon for a radar return to be possible. The aircraft is above the radar horizon if:

vhere:

Z is a unit vector directed along the zenith of the reporting radar as follows:

$$\underline{Z} = \begin{cases}
X_{z} = \cos L_{r} \cos \lambda_{r} \\
Y_{z} = \cos L_{r} \sin \lambda_{r} \\
Z_{z} = \sin L_{r}
\end{cases} (A-3)$$

 $\boldsymbol{L}_{r},\;\boldsymbol{\lambda}_{r}$ are the geographic latitude and longitude of the reporting radar

The azimuth angle θ is calculated as follows.

$$\theta = \tan^{-1} \left[\frac{\underline{S} \cdot \underline{E}}{\underline{S} \cdot \underline{N}} \right] \tag{A-4}$$

where:

<u>E</u> is a unit vector directed due east of the reporting radar as follows.

$$\underline{\mathbf{E}} = \begin{cases} \mathbf{X}_{\mathbf{E}} = -\sin \lambda_{\mathbf{r}} \\ \mathbf{Y}_{\mathbf{E}} = \cos \lambda_{\mathbf{r}} \\ \mathbf{Z}_{\mathbf{E}} = \mathbf{0} \end{cases}$$
 (A-5)

 $\underline{\mathbf{N}}$ is a unit vector directed due north of the reporting radar as follows.

$$\underline{N} = \begin{cases}
X_{N} = -\sin L_{r} \cos \lambda_{r} \\
Y_{N} = -\sin L_{r} \sin \lambda_{r} \\
Z_{N} = \cos L_{r}
\end{cases}$$
(A-6)

APPENDIX II

SIMULATED DATA FOR THE SEVEN JSS REGIONS

Radar slant range and azimuth data were generated for four aircraft locations at altitudes of 30,000, 45,000 and 60,000 feet in each JSS region. For a particular radar, a slant range azimuth pair was generated if the aircraft was within 250 nmi of the radar and above the radar horizon. Radar slant ranges were converted into stereographic ground ranges using the SAGE/BUIC and JSS ground range equations. Stereographic ground ranges were transformed into coordinates on the common coordinate plane. The actual coordinates on the common plane were also obtained. The registration errors induced by the SAGE/BUIC and JSS ground range equations were calculated.

For each JSS region, there is a Site Data, Simulated Radar Data, and Registration Errors table. In addition, there is a figure showing radar site, aircraft, and region center locations.

Explanation of Tables

The Site Data Table shows the following.

- a) Approximate latitude and longitude of the radar sites and region center.
- b) The earth radius to each radar site calculated using equation (12).
- c) Coordinates on the common plane for the radar sites calculated using equations (13) and (14).
- d) The radius of the conformal sphere calculated using equation (27).

The Simulated Radar Data Table shows the following.

- a) The latitude, longitude and altitude of the aircraft.
- b) The slant range and azimuth for all reporting radars. A

radar is a reporting radar if the target is within 250 nmi and above the radar horizon. Slant range and azimuth data are calculated using the algorithm in Appendix I.

The Registration Error Table shows the following.

- a) The stereographic ground range calculated using the SAGE/ MUIC and JSS ground range equations (equations (8) and (9)).
- b) Coordinates on the common plane obtained from the SAGE/BUIC and JSS stereographic ground range equations using equations (16) and (17).
- c) Coordinates on the common plane obtained from the actual location of the aircraft using equations (13) and (14).
- d) The registration error induced by the SAGE/BUIC and JSS stereographic ground range equations.

TABLE BI SITE DATA - MORTHEAST JSS REGION

	31.15	SITE LOCATION		EARTH RADTHS	COORDIA	COORDINATES ON
		APPEC	APPECK IMATE	TO SITE	THE COM	THE COMOON PLANE
SITE	DESIGNATION	LATITUDE	LONCITUDE	m S	×	À
-	BENSON, MC	35.4	78.6	3440.184	93.379	-495.951
~	ROSDIK, KA	45.4	71.7	3439.806	416.372	-54.479
-	BUCKS RARBOR, WE	46.6	68.8	3438.351	757'667	89.369
-3	CLEVELAND, OH	41.5	61.7	3438.987	-53.965	-131.216
•	DETROIT, WI	42.3	83.1	3438.826	-115,445	81,965
¢	DÜBATS, PA	41.1	78.8	3439.067	76.925	-154.757
~	DAPIRE, 42	8.75	65.1	3438.321	-238.529	73.930
•	FINLAND, MY	47.6	91.3	3437.795	-438.855	251.055
٥	BARTFLED, CT	8.13	72.7	3438.926	348.913	-97.562
2	IVOR, VA	16.9	76.9	1419,896	173.299	879.607-
=	NEW YORK, MY	40.7	74.0	3439.147	295.843	-168.207
2	TREVASE, PA	40.1	75.0	3439.267	252.658	-207.271
2	UTICA, IN	43.1	75.2	3438.665	232.255	-28.533
4	менижний, вс	18.9	77.0	3439.505	163.712	-283.874
22	RECTOR CENTER	43.7	80.5	•	0.000	00.0
	2	BIUS OF THE	LABIUS OF THE CONFORMAL SPHEME	SPHERE - 3428.842	42	

SDATLATED RADAR DATA - NORTHEAST JSS REGION

CASE	ATRCANT	AIRCRAFT LOCATION	ALTITUDE (K-FT)	REPORTING RADAR(S)	SLANT RANGE (Net)	AZTMUTE
1	50.0	89.1	30	FINLAND, MN	179.102	28.432
7	50.0	1.68	45	FINLAND, MN	179.251	28.432
٣	50.0	1.69	09	FINLAND, HIN	179.434	28.432
•	47.0	83.2	30	DPIRE, HI	179.690	41.591
\$	0.54	83.2	65	DIPIRE, HI	179.749	41.591
9	47.0	83.2	99	EWIRE, MI	179.931	41.591
7	40.0	85.7	30	DETROIT, MI	178.666	220.236
8.8 815	40.0	85.7	45	DETROIT, MI CLEVELAND, OH	178.815 199.594	220.236 244.455
98 98	60.0	85.7	09	DETROIT, MI CLEVELAND, OH	178.998 199.772	220.236 244.455
10	34.0	81.8	30	BERSON, NC	179.315	243.007
11	34.0	81.8	59	BENSON, NC	179.464	243.007
12	34.0	81.8	09	BENSON; NC	179.647	243.007

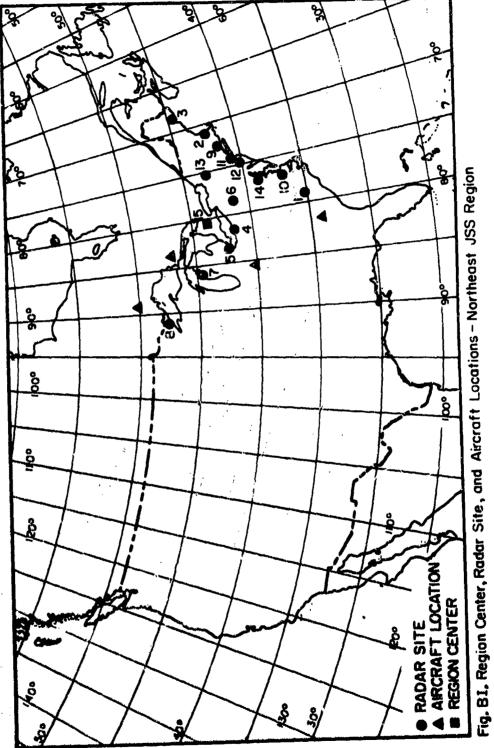


TABLE BIII REGISTRATION ERRORS - NORTHEAST JSS REGION

CASE # BUIC/SAGE JSS X Y 1 178.820 178.355 -332.586 39 2 178.864 178.419 -332.548 39 4 179.317 178.824 -110.443 19 5 179.382 178.888 -110.397 19 6 179.446 178.951 -110.352 19 7 178.335 177.867 -234.911 -21 8a 178.448 177.931 -234.953 -21 8b 199.219 198.632 -235.096 -21 9a 178.512 177.994 -234.996 -21 9b 199.290 198.703 -235.161 -21	JSS A	5.5	ACTUAL		2/ 4004	ŝ
## BUIC/SAGE JSS 178.820 178.355 178.884 178.419 178.949 178.888 179.317 178.888 179.446 178.951 178.335 177.867 178.448 177.931 199.219 198.632 198.290 198.703	^			1.	EXKUK (FF)	
178.820 178.355 178.884 178.419 178.949 178.483 179.317 178.824 179.382 178.888 179.446 178.951 178.448 177.931 178.448 177.931 199.219 198.632	v	Y	×	X	BUIC/SAGE	JSS
178.864 178.419 178.949 178.483 179.317 178.824 179.382 178.888 179.446 178.951 178.335 177.867 8 178.448 177.931 8 178.512 177.994	396.033 -332.864	395.656	-332.763	395.778	0.310	0.158
178.949 178.483 179.317 178.824 179.382 178.888 179.446 178.951 178.335 177.867 b 199.219 198.632 a 178.512 177.994 b 199.290 198.703	396.085 -332.826	395.708	-332.763	395.778	0.374	0.094
179.317 178.824 179.382 178.888 179.446 178.951 178.335 177.867 b 178.448 177.931 b 199.219 198.632 a 178.512 177.994 b 199.290 198.703	396.137 -332.788	395.760	-332.763	395.778	0.439	0.031
179.382 178.888 179.446 178.951 178.385 177.867 178.448 177.931 199.219 198.632 178.512 177.994	199.647 -110.796	199.301	-110.676	199.402	0.339	0.156
179.446 178.951 178.335 177.867 178.448 177.931 199.219 198.632 177.994 177.994 199.290 198.703	199.692 -110.750	199.346	-110.676	199.402	0.403	0.092
178.335 177.867 178.448 177.931 199.219 198.632 178.512 177.994 199.290 198.703	199.737 -110.705	199.391	-110.676	199.402	0.467	0.030
178.448 177.931 199.219 198.632 178.512 177.994 199.290 198.703	-214.665 -234.564	-214.280	-234.645	-214.383	0.387	0.131
178.512 177.994 199.290 198.703	-214.713 -234.607 -214.574 -234.562	-214.327 -214.328	-234.645	-214.383	0.451	0.068
	-214.760 -234.649 -214.604 -234.627	-214.375	-234.645	-214.383	0.515 0.561	0.010
10 179.033 178.443 -65.503	-580.774 -64.979	-580.495	-65.095	-580.572	0.455	0.132
11 179.097 178.507 -65.560	-580.805 -65.036	-580.526	-65.095	-580.572	0.520	0.075
12 179.161 178.571 -65.617	-580.835 -65.092	-580.556	-65.095	-580.572	0.584	0.016

TABLE BIV

SITE DATA - NORTHWEST JSS RECION

	SITE	SITE LOCATION		EARTH RADIUS	COOKDI	COORDINATES ON
		APPRO	APPROXIMATE	TO SITE	THE COM	THE COMMON PLANE
SITE #	DESIGNATION	LATITUDE	LONGITUDE	E	×	>
П	BEACH, ND	6.94	104.0	3437.896	311.418	122.482
2	FINLEY, ND	47.5	0.86	3437.775	550.135	190.838
8	KALISPELL, MT	48.2	114.0	3437.634	-96.064	186.916
77	KENO, OR	42.1	121.9	3438.866	-458.105	-150.961
5	KLAMATH, CA	41.5	124.0	3438.987	-556.568	-173.879
9	MAKAH, WA	7.87	124.8	3437.594	-525.023	241.556
7	MALSTROM, MT	8.72	111.2	3437.714	16.132	161.551
SS	HICA PEAK, WA	67.5	117.0	3437.775	-218.925	150,996
6	SALEM, OR	6.44	123.0	3438.301	-483.632	22.063
97	REGION CENTER	45.1	111.6	•	0.000	0.000
		RADTUS	OF THE CON	RADIUS OF THE CONFORMAL SPHERE = 3425.636	3425.636	

TABLE BY

SIMULATED RADAR DATA - NORTHWEST JSS REGION

	AIRCRAFT	IRCRAFT LOCATION	ALTITUDE	REPORTING	SLANT	
CASE #	LATITUE	LONGITUDE	(K-FT)	RADAR (S)	RANGE (NM)	AZIMUTH
1	50.0	128.7	30	MAKAH, WA	181.212	303.515
2	50.0	128.7	57	MAKAB, WA	181.361	303.515
3	50.0	128.7	09	MAKAH, WA	181.543	303.515
4	39.0	126.2	30	KLAMATH, CA	180.949	214.707
5	39.0	126.2	45	KLAMATH, CA	181.097	214.707
6	39.0	126.2	09	KLAMATH, CA	181.280	214.707
7	50.0	108.1	30	MALMSTROM, MT	180.466	41.732
8	50.0	108.1	45	MALMSTROM, MT	180.615	41.732
98 95	50.0	108.1	09	MALMSTROM, MT BEACH, ND	180.797 248.353	41.732
10	50.0	95.5	30	FINLEY, ND	180.126	32.542
11	50.0	95.5	45	FINLEY, ND	180.275	32.542
12	50.0	95.5	09	FINLEY, ND	180.458	32.542

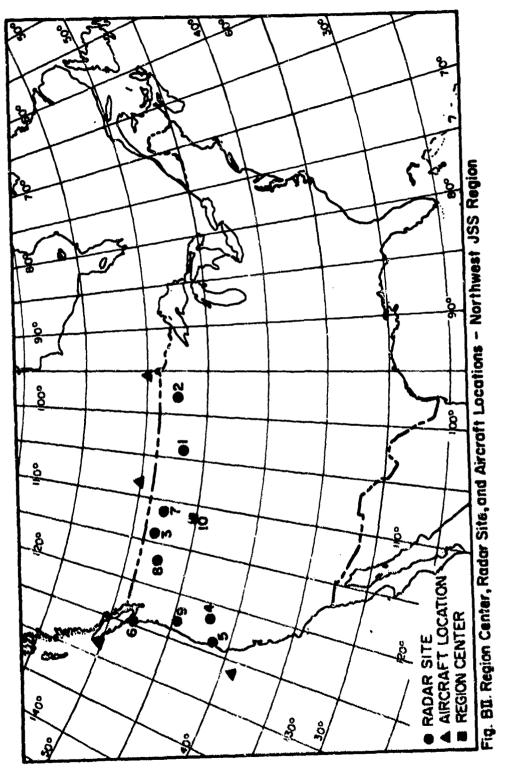


TABLE BVI REGISTRATION ENRORS - HORTHWEST JSS REGION

	STEREDGRAPHIC	APHIC		COORDINA	COORDINATES ON THE COMMON PLANE	COMMON PL	ANE		RECTSTRATION	200
	CROUND RANCE	ANCE	BUIC/SAGE	SAGE	ר	JSS	ACTUAL	AL	ERROR (NEW	
CASE 6	BUIC/SAGE	155	м	Ÿ	×	¥	×	Y	BUIC/SAGE	JSS
-	180.928	160.299	-658.214	366.469	151.753-	366.033	-657.877	366.134	.475	161
2	180.993	180.364	-658.262	366.513	-657.798	366.078	-657.877	366.134	.541	960
•	181.057	180.428	-658.309	366.559	-657.846	366.123	-657.877	366.134	909*	.033
,	180.635	179.964	-681.241	-306.922	-680,757	-306.922	-680.844	-306.510	.573	.136
~	180.729	180.029	-681.286	-306.970	-680.802	-306.452	-680.844	-306.510	.638	.071
٥	180.794	180.093	-681.330	-367.018	-680.846	-306.500	-680.844	-306.510	. 703	.010
,	180.182	179.550	135.567	296.718	135.148	296.244	135.262	296 33	.476	.158
60	180.247	179.614	135.610	296.767	135.196	295.292	135.262	296.353	.541	.094
93 93	180.312 247.859	175.579	135.652	296.816	135.233	296.341 296.283	135.262	246,353	.606	.031
20	179.843	179.209	619.914	358.294	619.669	357.702	619.739	357.845	.482	.160
11	179.907	179.273	619.939	358.354	619.693	357.762	619.739	357.845	.547	.093
27	179.972	179.337	619.963	358.414	619.718	357.822	619.739	357.845	.612	.031

TABLE BVII

SITE DATA - SOUTHEAST JSS REGION

	SITE	LOCATION		FARTH RADIUS	COORDINATES	ES ON
		APPROXIMATE	MATE	TO SITE	THE COMMON PLANE	N PLANE
SITE #	DESIGNATION	LATITUDE	LONG I TUDE	Ë 8	Х	Ā
-	CROSS CITY, FL	26.7	81.7	3441.729	402.130	-142.802
2	DAUPHIN ISLAND, AL	30.3	88.1	3441.121	56.970	29.945
2	ELLINGTON, TX	29.6	95.2	3441.243	-312.965	25.924
7	GRAND BAY, AL	30.5	86.4	3441.086	144.730	73.363
5	JEDBERG, SC	33.4	80.0	3440.561	761.596	264.072
9	KEY WEST, FL	24.6	82.0	3442.058	393.289	-269.288
1	LACKLAND, TX	7.62	98.7	3441.277	689.965-	26.093
80	LAKE CHARLES, LA	30.2	93.2	3441.138	-207.382	57.280
6	MACDILL, FL	27.8	82.6	3441.548	350.265	-79.885
10	NEW ORLEANS, LA	30.5	6.68	3441.086	-36.178	71.718
111	OILTON, TX	27.8	99.2	3441.548	-530.944	-67.401
12	PATRICK, FL	28.6	80.7	3441.414	962.794	-25.737
113	RICHMOND, FL	25.7	7.08	3441.888	761.92	-197.948
7.7	TYNDALL, FL	30.1	85.6	3441.156	186.829	50.631
15	WHITE HOUSE, FL	56.62	81.8	3441.191	384.905	48.034
16	REGION CENTER	29.3	89.2	1	0000	0.000
	RADIUS	50	THE CONFORMAL SPHERE	ERE = 3430,619		

TABLE BVIII

SIMULATED RADAR DATA - SOUTHEAST JSS RECION

	ATRCRAF	T LOCATION	AT TOTAL SE	t propertion	1 27 4 1977	
CASE !	LATITUDE	TITUDE LONGITUDE	(K-FT)	RADAR(S)	RANGE (NM)	AZIMUTH
7	33.0	76.5	30	JEDBERG, SC	178,009	96.780
2	33.0	76.5	59	JEDBERG, SC	178.158	96.780
3	33.0	76.5	09	JEDBERG, SC	178.341	96.780
4	28.0	77.4	30	ı	178.609	100.822
54 5b	28.0	27.42	59	PATRICK, FL RICHMOND, FL	178.758 212.001	100.822
68 68 60	28.0	77.4	09	PATRICK, FL RICHMOND, FL CROSS CITY, FL	178.941 212.276 243.036	100.822 48.810 70.316
7	24.0	85.2	30	KEY WEST, PL	179.216	259.100
8	24.0	65.2	45	WEST.	179.365	259.100
6	24.0	85.2	09	KEY WEST, FL	179.547	259,100
10	27.5	0.06	30	NEW ORLEANS. LA	179.798	181.704
11a 11b	27.5	90.0	5%	NEW ORLEANS, LA DAUPHIN IS., AL	179.947 195.491	181.704
12s 12b 12c	27.5	0.08	09	NEW ORLEANS, LA DAUPHIN IS., AL LAKE CHARLES, LA	180.130 195.670 234.010	181.704 211.308 132.999

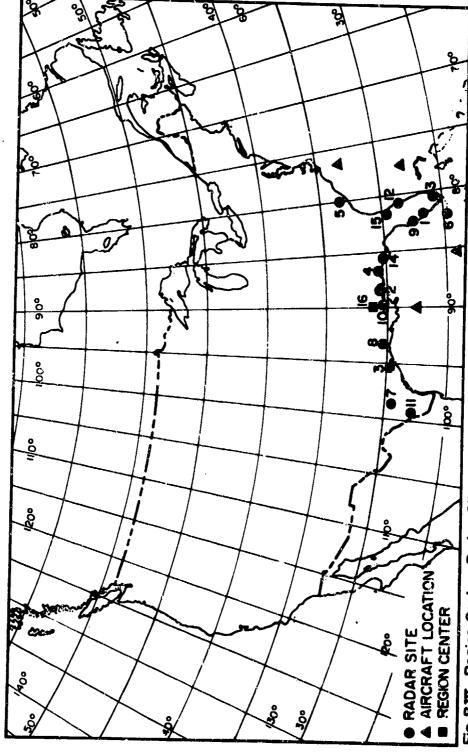


Fig. BIII. Region Center, Radar Site and Aircraft Locations - Southeast JSS Region

TABLE BIX RECESTRATION ERRORS - SOUTHEAST JSS RECTION

Г	٦	٦				7		T		٦٦	T		7	7		_			乛
NO	3	JSS	.144	.081	.022	.164	.081	.020	.060	.102	.144	.080	.019	.130	.065	.085	.001	.016	٠٥٥
RECISTRATION	ERROR (NE)	BUIC/SACE	.375	.439	. 503	.420	. 363	.548	.639	.688	.453	.517	, 581	.416	.480	. 516	345,	.580	750.
	IAL	٨	257.610	257.610	257.610	-46.722	-46.722		-46.722		-312.860	-312.860	-312,860	-107.245	-107.245			-107.245	
ANE.	ACTUAL	×	640.205	640,205	640.205	625.535	625.535		625.535		219.539	219.539	219.539	-42.560	-42.560			-42.560	
COORDINATES ON THE COMMON PLANE	Jss	Å	257.631	257.628	257.626	-46.692	-46.700	-46.707	-46.754	-46.741	-312,814	-312.829	-312.845	-107.115	-107.179	-107.168	-107.246	-107.228	-10/.192
ATES ON THU		×	640.063	640.126	640.190	625.394	625.458 625.431	625.521	625.484	625.435	219.675	219.613	219.551	-42.556	-42.558	-42.522	-42,551	-42.558	-42.393
COURDIN	BUIC/SAGE	¥	257.611	257,609	257.667	-46.758	-46.766	-46.773	-46.256	-46.429	-312.958	-312.973	-312.989	-107.660	-107.724	-107.679	-107,789	-107.739	-107.692
	BUIC,	×	640.580	640.644	640.708	625.953	626.017 625.920	626.080		626.158	219.097	219.035	218.973	-42.575	-42.578	-42.826	-42.580		-42.088
DCRAPH1C	D RANGE	SSf	177.215	177.278	177.341	177.769	177.832 211.025	177.896	211.101	241.763	178.340	178.404	178.467	178.970	179.035	194.522	179.099		232.810
STEREOGR	GROUND R	BUIC/SAGE	177.728	177.791	177.855	178.327	178.391 211.718	178.455	211.793	242.545	178.934	178.998	179.062	179.516	179.580	195.117	179.645	195.187	233.323
		CASE #	1	2	3	7	5 48	2,4	£	ود	7	8	6	10	11.4	115	128	12b	771

-35

FABILE BX

SITE DATA - SOUTHWEST JSS REGION

	SITE	SITE LOCATION		EARTH RADIUS	COORDINATES ON	res on
		APPROX IMA TE	IMATE	TO SITE	THE COMMON PLANE	IN PLANE
SITE #	DESIGNATION	LATITUDE	LONGITUDE	er ex	×	¥
7	EL PASO, TX	31.8	105.9	3440.854	347.065	-257.259
2	LAKE HAVASU, AZ	34.5	115.0	3440.355	-113.710	-106.173
3	MT LAGUNA, CA	32.8	116.4	3440.671	-186.670	-205,609
7	OAKLAND, CA	38.0	1.22.8	3439.682	-477.514	126.934
5	ODESSA, TX	32.9	102.8	3440.653	498.919	-178.606
9	PASO ROBLES, CA	36.0	120.5	3440.070	-378.503	-2.762
7	PHOENIX, AZ	33.5	112.1	3440.542	30.020	-167.118
œ	POINT ARENA, CA	38.9	123.7	3439.505	-513.764	185.416
6	SAN PEDRO, CA	33.8	118.3	3440.486	-279.209	-141.482
10	SILVER CITY, NM	32.9	108.8	3440.653	196.527	-199.258
11	REGION CENTER	36.3	112.7	7	0.000	000.0
	RADIUS OF		THE CONFORMAL SPHERE = 3428.877	= 3428.877		

TABLE BXI

SIMULATED RADAR DATA - SOUTHWEST JSS REGION

	ATRCRAPT	T LOCATION	AL TTTTTE	RPPORTTME	STANT	
CASE #	LATITUDE		(K-FT)	RADAR (S)	RANGE (NM)	AZIMUTH
-1	39.0	127.5	30	POINT ARENA, CA	178.143	273.124
2	39.0	127.5	40	POINT ARENA, CA	178.292	273.124
3a 3b	39.0	127.5	09	POINT ARENA, CA OAKLAND, CA	178.475 229.828	273,124 286,604
4	34.0	123.2	30	PASO ROBLES, CA	179.237	228.788
5	34.0	123.2	45	PASO ROBLES, CA	179.386	228.787
68 66 60	34.0	123.2	09	PASO ROBLES, CA OAKLAND, CA SAN PEDRO, CA	179.569 240.948 245.494	228.787 184.764 274.168
7	30.0	117.7	30	MT LAGUNA. CA	180.610	202.056
8	30.0	117.7	45	MT LAGUNA, CA	180.759	202.056
9a 9b	30.0	117.7	09	MT LAGUNA, CA SAN PEDRO, CA	180.942 230.076	202.056 172.168
10	28.8	106.0	30	EL PASO, TX	179.830	181.682
11	28.8	106.0	45	EL PASO, TX	179.980	181.682
12	28.8	106.0	99	EL PASO, TX	179.980	181.682

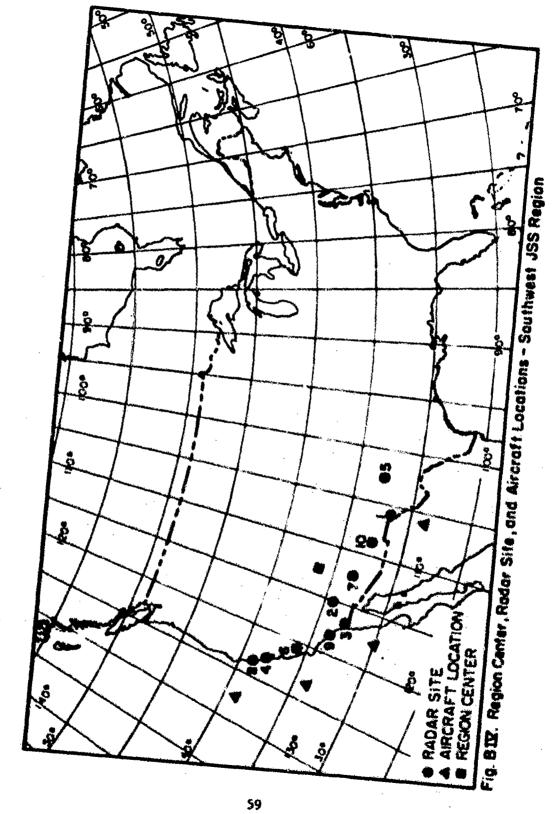


TABLE SELL RECENTRATION MACHES - SOUTHWEST 155 RECTOR

Γ		T												
OK	-	788	.148	8.	.024	.136	240.	.011 .058 .102	.136	.070	.007	181.	990.	.002
RECISTRATION	TROR (P	MIC/SAGE	*04.	.472	. 536 . 645	699"	715.	. 578 . 700 . 732	587.	. 550	.615	769.	. 562	.627
	719	Ý	215.866	215.864	215.864	-109.837	-109.837	-109.837	-370.179	-370.179	-170.179	-437.084	-437.094	-437.094
ME	ACTUAL	X	-690.100	-690.100	-690.100	-522.270	-522,270	-522.270	-260.374	-260.374	-260.374	353.471	153.471	353.671
COORDINATES OF THE COMMING PLANT	\$\$	À	23.5.854	215.865	215.875	-109.749	-109.788	-109,526 -109,780 -109,823	-370.055	-370.116	-370.175	-435.963	-637.028	-437 092
TAS ON THE		X	-689.953	-410.016	-650.079 -650.015	-522.167	-522.218	-\$12.269 -\$22.260 -\$22.168	-260.324	-260.150	-260.376 -266.376	153.467	353,469	353.471
COOKDING	Sales.	Å	215.948	215.939	215.970	-522.635 -110.098	-522.686 -110.137	-512.138 -110.176 -522.199 -110.525 -522.991 -109.715	-370.620	-370.680	-260.430 -370.739	153.489 -437.591	151.491 -437.655	353.483 -437,721
	ETC.	×	-490.500	-690.563	-490,626	-522.635	-522.686	-522.13 -522.99 -522.991	-360.577	-260,603	-260.630	151.489	153.481	151.481
THE COLUMN	SEC.	355	137.313	137.376	177.639 228.622	118, 17 1	178.637	176.501 239.703 244.176	139.715	174.734	179.839 228.615	178.924	178.988	174.052
STEREDISEASE	CHOCKE E	Tale/sacr	157.861	172.935	224.341	178.955	179.019	240.458	160.327	163.192	180.652	179.548	179.612	179.877
		CAS2 /	-	~	22		-	242	-	•	**	02	=	27

TABLE BKIII SITE DATA - EASTERN CANADIAN JSS REGION

	SITE	LOCATION		EARTH PADIUS	COORDINATES ON	TES ON
		APPRO	APPROXIMATE	TO SITE	THE COMMON PLANE	N PLANE
SITE	DESIGNATION	LATITUDE	TOMETUBE	E	×	¥
C-1	BEAUSEJOUR, MAN	50.1	9.96	3437.253	-760.697	-9.238
C-2	GYPSIMVILLE, MAN	51.8	0.66	3436.916	-826.242	117.662
C-3	MONT APICA, QUE	48.0	71.8	3437.674	184.088	-232.865
Ç-4	LAC ST DENIS, QUE	46.0	75.0	3438.078	58.260	-357.336
0-5	ST MARGARETS, NB	47.0	65.5	3437.876	444.046	-266.025
g-0	SENNETERRE, QUE	48.3	77.8	3437.614	-55.714	-220.102
C-1	FALCONBRIDGE, ONT	46.2	81.0	3438.038	-190.642	-340.154
80	SIOUX LOOKOUT, ONT	\$0.2	91.9	3437.233	-590.254	-44.966
6-0	COOSE BAY, LABR	53.6	60.2	3436.564	571.518	160.071
C-10	GAMOR, WID	49.0	54.8	3437.473	839.591	-55.588
c-11	MOISIE, QUE	50.5	66,5	3437.173	375.718	-64.125
C-12	SYDNEY, NS	46.2	60.2	3438.038	668.436	-274.142
C-13	CHIBOUGAMAU, QUE	50.0	74.8	3437.273	61.488	-118.584
C-14	BARRINGTON, NS	43.5	65.8	3438.584	460.927	-475.666
C-15	LOWINER, ONT	49.5	83.1	3437.373	-259.965	-137.306
C-16	REGION CENTER	\$2.0	76.4	•	0.000	0.000
	RADII	US OF THE CO	ONFORMAL SPHE	BADIUS OF THE CONFORMAL SPHERE = 3411.221		

TABLE BXIV

SIMULATED RADAR DATA - EASTERN CANADIAN JSS RECION

AIRCRAFT LOCATION
55.7
55.7
55.7
72.0
72.0
72.0
95.7
95.7
95.7
62.3
62.3
62.3

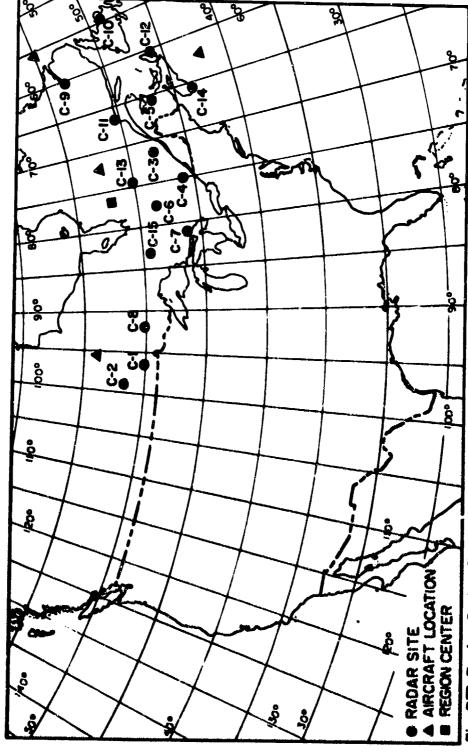


Fig. B.T. Region Center, Radar Site, and Aircraft Locations – Eastern Canadian JSS Region

TABLE BXV REGISTRATION ERRORS - EASTERN CANADIAN JSS REGION

	STEREOGRAHPIC	AHPIC		COURDINATES ON	TES ON THE	COMMON PLANE	ANE		RECISTRATION	NO
	GRAUND RANGE	ANGE	BUTC/SAGE	SAGE		JSS	ACTUAL	N.	ERROR (NH.)	₩)
CASE !	BUIC/SAGE	355	ĸ	Å	×	Y	×	Ϋ́	BUIC/SAGE	JSS
H	179.030	177.711	704.166	282.853	703.188	281.946	703.310	282.041	1.180	0.155
2	179.094	277.774	704.213	282.897	703.235	281.990	703.210	282.041	1.244	0.091
3	179.158	177.838	192.201	282.941	703.282	282.034	703.210	282.041	1.309	0.029
7	178.623	177.271	161.103	29.712	160.350	28.590	160.445	28.713	1.197	0.155
\$	178.687	177.335	161.139	29.766	160.385	28.643	160.445	28.713	1.261	0.092
83	178.751 235.828	177.396 234.049	161.174 158.910	29.819	160.420 160.543	28.695	160.445	28.713	1.325	0.030 n.099
7	178.335	177.004	-671.725	211.072	-672.877	210.378	-672.738	210.450	1.189	0.157
œ	178.399	177.067	-671.670	211.105	-672.823	210.412	-672.738	210.450	1.253	n.093
98 88	178.463 235.756	177.136 233.973	-671.615 -672.103	211.138 212.024	-672.768 -672.778	210.444	-672.738	210.450	1.318	0.030
10	178.850	177.438	629.795	-540.713	628.449	-540.196	628.575	-540.256	1.303	0.139
11	178.924	177.502	629.855	-540,737	628.509	-540.220	628.575	-540.256	1.368	0.075
12	178.988	177.565	629.91€	-540.760	628.569	-540.243	628.575	-540.256	1.433	0.015

TABLE BXVI

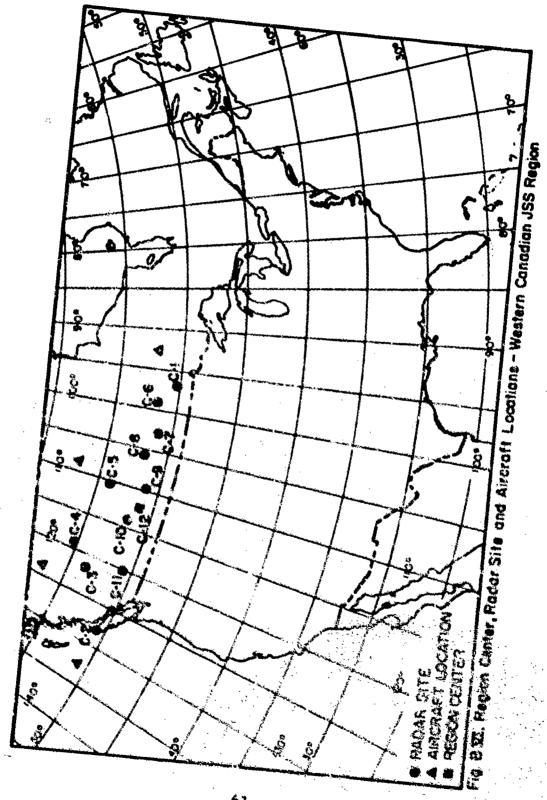
SITE DATA - WESTERN CANADIAN JSS REGION

ATES ON	THE COMMON FLANE	4.049	41.035	189.690	257.619	186.238	85.274	28.033	63.544	7.216	48.789	-1.543	0.000	
COORDINATES ON	THE COM	601.258	-601.122	-378.533	-243.268	56.215	484.381	349.035	228.883	82.707	-70.348	-302.978	0.000	
EARTH RADIUS	TO SITE E	3437.253	3437,133	3436.525	3436.256	3436.448	3436.916	3437.034	3436.876	3437.034	3436.896	3437.114	ı	
	LONGITUDE	7.96	128.0	122.8	119.2	110.5	0.66	102.8	105.9	109.9	114.0	120.1	112.1	
SITE LOCATION	LATITUDE LON	50.1	50.7	53.8	55.2	54.2	51.8	51.2	52.0	51.2	51.9	50.8	51.1	
SITE	DESIGNATION	BEAUSEJOUR, MAN	HOLBERG, BC	BALDY HUGHES, BC	BEAVERLODGE, ALTA	COLD LAKE, ALTA	GYPSUMVILLE, MAN	YORKTON, SASK	DANA, SASK	ALASKA, SASK	PENHOLD, ALTA	KAMLOOPS, BC	REGION CENTER	
	SITE #	C-1	C-2	C-3	7-5	C-5	9-3	C-7	8-3	6-3	01-2	C-11	C-12	

TABLE BAVII

SIMULATED RADAR DATA - WESTERN CANADIAN JSS REGION

TOTAL TIME TOTAL TANDERS			
LATITUDE LONGITUDE (K-FT)	T) RADAR (S)	RANCE (NM)	AZIMUTH
51.0 132.7 30	HOLBERG, BC	179.783	277.577
\$1.0 132.7 45	HOLBERG, BC	179.931	277.577
51.0 132.7 60	HOLBERG, BC	180.114	277.577
57.0 123.5 30	BEAVERLODGE, ALTA	180.652	308.603
57.0 123.5 45	BEAVERLODGE, ALTA MALDY HUGHES, BC	180.801 194.178	308.603 353.191
57.0 123.5 60	BEAVERLODGE, ALTA BALDY, HUGHES, BC	180.983 194.357	308.603 353.191
57.0 108.6 30	COLD LAKE, ALTA	180.485	20.236
\$7.0 108.6 45	COLD LAKE, ALTA	180.634	20.236
57.0 108.6 60	COLD LAKE, ALTA	180.816	20.236
52.0 92.7 30	BEAUSEJOUR, MAN	180.843	49.402
52.0 92.7 45	BEAUSEJOUR, MAN	180.991	707.67
52.0 92.7 60	BEAUSEJOUR, MAN GYPSUMVILLE, MAN	181.173 234.886	49.402
		69	60 BEAUSEJOUR, MAN GYPSUMVILLE, MAN



LABLE SEVILL

aft fotballed excise - western cambian jes apoton

	となるので 第二次の 無知のな	Librar.	de la participa de la companya de la	CXXXX	THE STATE OF THE COMPANY	COMPAGE FIL	ANE		AEC ISTRATION	NO
	CRUMING RAWLE	3	12.00	BU-TH. FYGADAR		\$5.		ACTUAL	ERRUR (NA)	Î
158 4	1 2 5 6 / VAL: F.	100	3	*		,	×	Å	BUIC/SAGE	355
-	2.4.2.0	4.	284.322-	548.503	-126.872	202.655	-771.020	102.692	. 551	.152
	106 9.1	47.8. M.1	.71.593	4367293	118,837	197,677	-111.020	102.692	616.	.088
-	#29. F31.	178.934	*\$4*800	585-201	165.022	669'20;	-771.620	102.692	.681	.027
•	\$21.CH	274, 25	- 172.917	152.040	-372.468	363.563	-372.591	383.682	867.	.158
23	110,000		500 mm	184, 645, 184, 288	\$12.515-	181.628 181.559	192.576-	383.682	. 563	.094
23	1 N (141 4 N (141		55	194.136 184.152	-372,262	183.673	-372.593	383.682	.627 .675	.032
	143, 542	220. 202	34 * 933	\$24.928	\$14,655	156.293	114.724	356.442	. 503	.160
	140.35	179,693	eur 711	156.985	114.620	356.354	114.724	356.442	. 567	960.
-	145.415	474, 6AF	14.932		114.707	356.424	114.724	356.442	.632	.032
63	140,259	524.822	160.838	356.351	656"812	148.678	711.015	148.796	. 554	158
1.4	\$20.025	179.9:4	4.1 - 217	490,344	310,04A	148.730	711.015	364.875	619.	760.
22.	216.117	211.506	\$55.45K \$51.793	144,350	716.927 716.926	145.782	711.015	148.796	789.	.031

TABLE BXIX

SITE DATA - ALASKAN JSS REGION

	SITE	SITE LOCATION		EARTH RADIUS	COORDINATES ON	TES ON
		APPROX	APPROXIMATE	TO SITE	THE COMMON PLANE	IN PLANE
SITE #	DESIGNATION	LATITUDE	LONGITUDE	ET &	Х	Å
1	CAPE LISBURNE	68.9	166.1	3433.972	-158.347	406.203
2	TIN CITY	65.6	168.0	3434,451	-228.125	214.751
3	KOTZEBUE	6.99	162.6	3434.256	-89.796	279,180
4	INDIAN MT	66.1	153.7	3434.375	124.323	233, 333
5	CAMFION	64.7	156.7	3434.590	53.998	145.056
9	FORT YUKON	9,99	145.2	3434,300	323.211	293.186
7	MURPHY DOME	65.0	148.4	3434,543	263.517	183,669
S)	TATILINA	62.9	1.56.0	3434.880	76.693	37.692
6	SPARREVON	61.1	155,6	3435,184	92.970	-69.769
10	FIRE ISLAND	61.2	150.2	3435,167	248.535	-49,613
11	KING SALMON	58.7	156.7	3435.607	65.641	-215,123
12	COLD BAY	55.3	162.9	3436.237	-140.719	-416.257
13	CAPE ROMANZOF	61.8	166.0	3435.064	-204.248	-18,689
14	CAPE NEWENIAM	58.6	162.1	3435.625	-103.432	-219.587
3 22	REGION CENTER	62.3	158.8	2	000.0	0.000
	RADIO	RADIUS OF THE CONFORMAL SPHERE - 3427.488	ORMAL SPHERE	3427.488		

TABLE BXX

SIMULATED RADAR DATA - ALASKAN JSS REGION

	AIRCRAFT	FLOCATION	ALTITUDE	REPORTING	SIANT	
CASE #	LATITUDE	LONGITUDE	(K-FT)	PADAR(S)	RANGE (NM)	AZIMUTI
	71.9	165.0	30	CAPE LISBURNE	182.265	6.500
2	71.9	165.0	45	CAPE LISBURNE	182.413	6.500
3	71.9	165.0	99	CAPE LISBURNE	182.595	6.500
4	0.39	174.0	30	TIN CITY	181.697	240.712
\$	64.0	174.0	4.5	TIN CITY	181.845	240.712
6	64.0	174.0	99	TIN CITY	182,027	240.712
7	56.0	168.1	30	COLD BAY	181.840	285.529
යුතු	56.0	168.1	57	COLD BAY	181.989	285.529
8	56.0	168.1	09	COLD BAY	182.171	285,529
10	58.2	150.0	30	FIRE ISLAND	180.750	177.983
13.4 13.5	58.2	150.0	57	FIRE ISLAND KING SALMON	180.899 213.608	177.983 95.237
12# 12b 12c	58.2	150.0	09	FIRE ISLAND KING SALMON SPARREVON	181.081 213.784 244.284	177.983 95.237 133.211

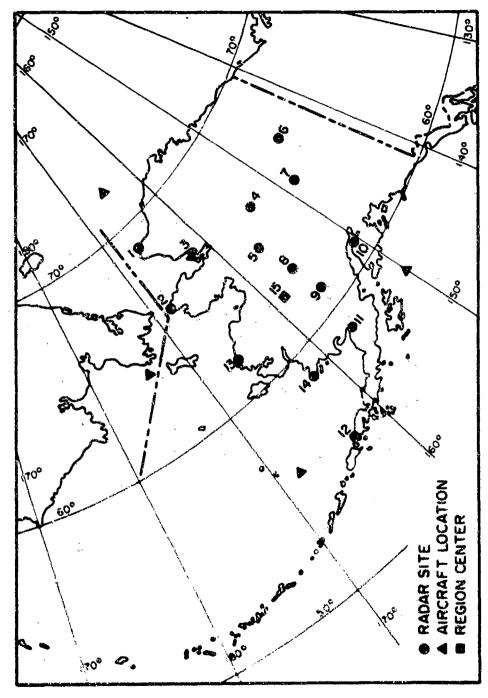


Fig BIII. Region Center, Radar Site, and Aircraft Locations-Alaskan JSS Region

TABLE BXX1

RECISTRATION ERRORS - ALASKAN JSS RECION

STERENGRAPHIC COORDINATES ON GROUND RANGE BUTC/SAGE WILC/SAGE X Y X X Y X X X X X	BUIC, SA	BUTC/SA	SAGE Y	The L		THE COMMON PLANE JSS Y	NNE ACTUAL	1	REGISTRATION ERROR (NM)	SON (SE
	181.980	181.637	-116.542	584.333	-	583.997	上三	584.149	.189	157
~	182.045	181.702	-116.527	584.397	-116.606	584.061	-116,582	584.149	. 254	.091
r.	182.116	181.767	-116.512	584.461	-116.591	584.124	-116.582	584.149	.320	.026
•	181.413	181.045	-397.830	149.306	-397.487	149.439	149.439 -397.618	149.379	.224	.145
5	181.477	181.110	-397.891	149.282	-397.547	149.415	149.415 -397.638	149.379	.289	.080
*	181.542	181.174	-397.951	149.259	149.259 -397.607	149.392	149.392 -397.618	149.379	.354	.017
•	121.556	181.094	-312.948	-356.503	-312.511	959.956-	-312.662	-356.620	. 309	.156
30	181.621	181.159	-313.010	-356.482	-312.572	-356.635 -312.662	-312.662	-356.620	.374	.091
٥	181.686	181.224	-313.071	-356.460 -312.633	-312.633	-356.613	-312.662	-356.620	.439	.030
10	180.467	180.064	278.472	-227.893	278.405	-227.495	278.426	-227.623	.274	.129
114 116	180.532 213.225	180.129	278.483	-227.957	278.416 278.301	-227.559	278.426	-227.623	.339	.065
12a 12b 12c	180.596 213.301 243.793	180.193 212.797 243.247	278.493 278.881 278.794	-228.021 -227.630 -227.917	278.427 278.377 278.377	-227.622 -227.601 -227.563	278.426	-227.623	.404	.001 .053 .077
							A			